

Exam #1

Do all three problems. Weights: #1 - 25%, #2 - 35%, #3 - 40%. Closed book, closed notes. Be sure your answers are presented in a neat and well-organized manner.

1. Answer **True** or **False** for each of the following statements. If the statement is false, indicate how it could be changed to a true statement with a small change in the wording.

a. Given $F : \mathfrak{R}^n \rightarrow \mathfrak{R}$ differentiable. $F(\cdot)$ is concave if and only if

$$F(u) < F(v) + \frac{\partial F}{\partial x}(v)(u - v) \quad \text{for all } u, v \in \mathfrak{R}^n, u \neq v.$$

b. For $F : \mathfrak{R} \rightarrow \mathfrak{R}$, if $F(\cdot)$ is either strictly increasing or strictly decreasing, then $F(\cdot)$ is strictly quasi-concave.

c. $F : \mathfrak{R}^n \rightarrow \mathfrak{R}$ is differentiable and $x^* \in \mathfrak{R}^n$. If $\frac{\partial F}{\partial x}(x^*) = 0$ and $\frac{\partial^2 F}{\partial x^2}(x^*)$ is negative definite then x^* is a strict local maximum of $F(\cdot)$.

d. In an equality-constrained optimization problem with 3 choice variables ($n = 3$) and 2 constraints ($m = 2$), the bordered Hessian is a 5×5 matrix and the second order necessary condition is a single sign restriction on the determinant of the entire bordered Hessian.

e. Let $F : \mathfrak{R}^n \rightarrow \mathfrak{R}$ and $g : \mathfrak{R}^n \rightarrow \mathfrak{R}$ be differentiable and let $x^* \in \mathfrak{R}^n$ be a point such that $\frac{\partial g}{\partial x}(x^*) \neq 0$. Then x^* is a local solution to

$$\max_{w.r.t. x} F(x) \quad \text{such that} \quad g(x) = b$$

if and only if there exists $\lambda^* \in \mathfrak{R}$ such that (x^*, λ^*) is a stationary point of

$$L(x, \lambda) \equiv F(x) + \lambda[b - g(x)].$$

2. Consider the problem:

$$\min_{w.r.t. x} a \cdot x \quad \text{such that} \quad x \in U,$$

where x is an $n \times 1$ vector of choice variables, a is a $1 \times n$ vector of parameters, and $U \subset \mathfrak{R}^n$. Suppose that the problem has a global solution, $x^*(a)$, for all $a \in \mathfrak{R}^n$, and define the value function $F^*(a) \equiv a \cdot x^*(a)$.

(Some facts that you don't need to prove: A sufficient condition for the problem to have a global solution for all $a \in \mathfrak{R}^n$ is that U is closed and bounded. While the optimal value of x , $x^*(a)$, need not be unique for a given a , the value function is uniquely defined. That is, if, for a given a , there are multiple optimal x^* s, they all yield the same value of the objective function.)

Prove that $F^* : \mathfrak{R}^n \rightarrow \mathfrak{R}$ is concave.

3. Consider the following equality-constrained maximization problem:

$$\max_{w.r.t. x_1, x_2, x_3} f(x_1, x_2, x_3) \quad \text{such that} \quad g(x_1, x_2, x_3) = b \quad (i.)$$

where $f : \mathfrak{R}^3 \rightarrow \mathfrak{R}$ and $g : \mathfrak{R}^3 \rightarrow \mathfrak{R}$ are differentiable functions and b is a constant. Also consider the unconstrained optimization problem:

$$\max_{w.r.t. x_1, x_2} F(x_1, x_2) \quad (ii.)$$

where $F : \mathfrak{R}^2 \rightarrow \mathfrak{R}$ is differentiable.

a. Write down the Lagrangian and the first-order conditions for problem (i.).

b. Write down the first-order conditions for problem (ii.).

Now suppose that $g(x_1, x_2, x_3) = x_3 - h(x_1, x_2)$ where $h : \mathfrak{R}^2 \rightarrow \mathfrak{R}$ is differentiable, and that $F(x_1, x_2) \equiv f(x_1, x_2, h(x_1, x_2) + b)$. For this case, show that

c. if (x_1^*, x_2^*, x_3^*) satisfies the first-order conditions for problem (i.), then (x_1^*, x_2^*) satisfies the first-order conditions for problem (ii.).

d. if (x_1^*, x_2^*) satisfies the first-order conditions for problem (ii.), then $(x_1^*, x_2^*, h(x_1^*, x_2^*) + b)$ satisfies the first-order conditions for problem (i.).