# A Java Reinforcement Learning Module for the Recursive Porous Agent Simulation Toolkit

Facilitating study and experimentation with reinforcement learning in multi-agent, social science simulations

Presented by Charles Gieseler

#### **Overview**

- Agent based simulation in the Social Sciences
- The Recursive Porous Agent Toolkit (Repast)
- What is the JReLM?
- General Architecture
- Pre-implemented Structures
  - Supporting Classes
  - Graphical User Interface

- Roth-Erev Learning
- Implementation of Roth-Erev algorithms
- The Raita Economy: An Illustrative Application
- Testing and Validation
- Ongoing and future work



# Agent-based Simulation in the Social Sciences\*

- Social systems:
  - Patterns of the whole emerge from interaction of the many
- Agent-based Simulation
  - Computational Agents: Autonomy, self-directed action
  - Useful metaphor for studying social systems
- Emergent patterns in simulation can give insight into real world systems

<sup>\*</sup> Beginner's Guide http://www.econ.iastate.edu/tesfatsi/abmread.htm

# Adaptive behavior in Social Science Simulation

- Agent-based simulation a bottom-up approach
- Behavior of individuals affect macro-scale patterns
- Adaptive behavior more appropriate for metaphors of social systems
- AI, Machine Learning, Cognitive-based methods

# Agent-Based Computational Economics\*

- Study of economic systems using simulation models of interacting agents
- Approach gaining importance in the economics community
- North-Holland/Elsevier Handbook of Computational Economics Series: Volume 2 Agent-Based Computational Economics
  - Edited by L. Tesfatsion and K. Judd

<sup>\*</sup> Collection of ACE resources http://www.econ.iastate.edu/tesfatsi/ace.htm

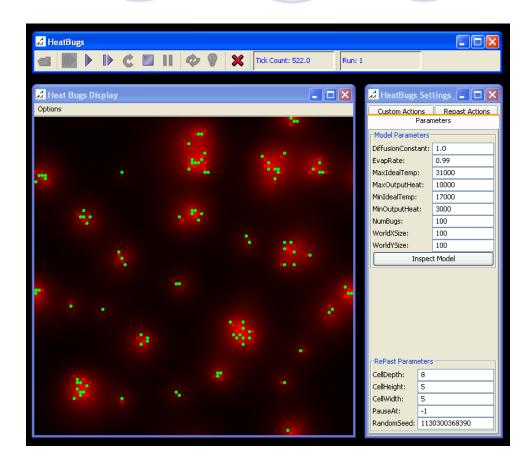
#### Simulation use and programming

- Client
  - Programs in the language of the toolkit
  - Designs and implements the program components
  - Builds experimental workbench

- User (or End User)
  - Runs the simulation, usually through the Graphical User Interface (GUI)
  - Designs the experimental setup
  - Performs
     experimentation and
     analysis of results

# The Recursive Porous Agent Toolkit (Repast)

- "a specification for agent-based modeling services or functions" \*
- Motivated by Swarm
- Sallach (U of Chicago), Collier, Howe, and North (Argonne National Lab)
- Repast Organization for Architecture and Development (ROAD)
- Current version 3.1
- Three flavors: RepastJ, Repast.NET, RepastPy



<sup>\*</sup> Repast homepage http://repast.sourceforge.net/

### **Popularity of Repast**

- Evaluation of free java-libraries for socialscientific agent based simulation, Tobias and Hoffman, 2004 \*
  - Comparison of freely available agent-based simulation platforms
  - Five categories of detailed criteria, geared towards
    Social Science study
  - Repast the best
- Currently the primary tool used by the ACE group in the Department of Economics

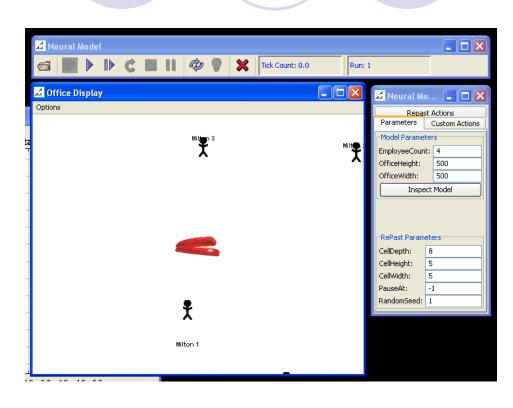
<sup>\*</sup> Available at http://ideas.repec.org/a/jas/jasssj/2003-45-2.html

#### Structure of a Repast simulation

- Model: defines and runs the simulation
- Space: The environment or world which agents inhabit
- Dynamic GUI:
  - Displays and charts
  - Custom parameter settings
- Agents: Open, client defined
  - Allows for flexibility
  - Can be burdensome if more complex behavior is required

#### Adaptive behavior in Repast

- Genetic Algorithm demo model
- OpenForecast demo model
- Java Object Oriented Neural Engine (JOONE)
  - Wrapper and demo
- Must custom implement other methods
  - Hard for the novice
  - Time consuming for the expert



#### What is JReLM?

# Java Reinforcement Learning Module

- Platform for implementing and using reinforcement learning in Repast
- Ease the burden of design and implementation for the client
- Allow the user to manage learning settings through the Repast GUI
- Designed specifically for use in RepastJ
- Open Source, Release with Repast

#### What JReLM offers

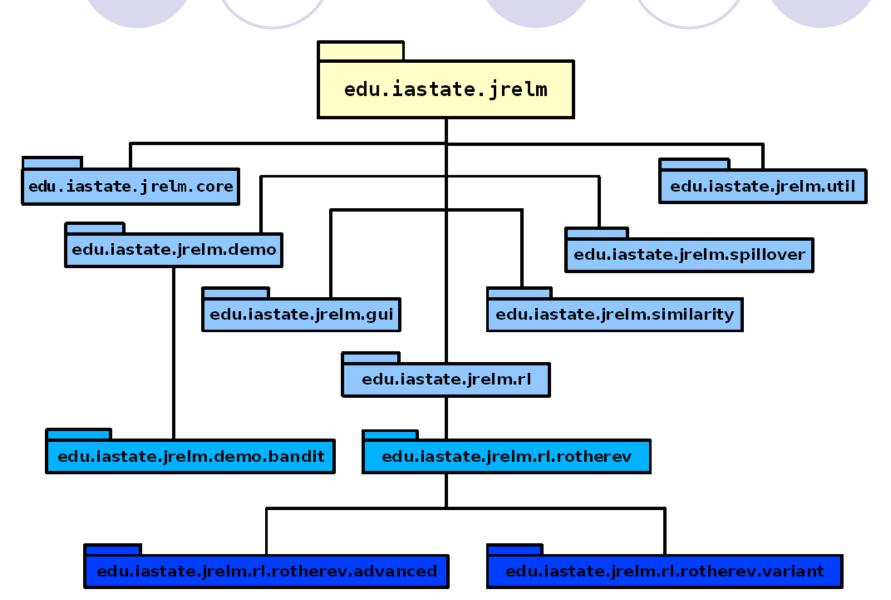
- Platform for algorithm implementation
  - Framework of structures common to many types of reinforcement learning
- Includes algorithms currently in use in social science applications
- Graphical User Interface
- Integrated into Repast

#### **General Architecture**

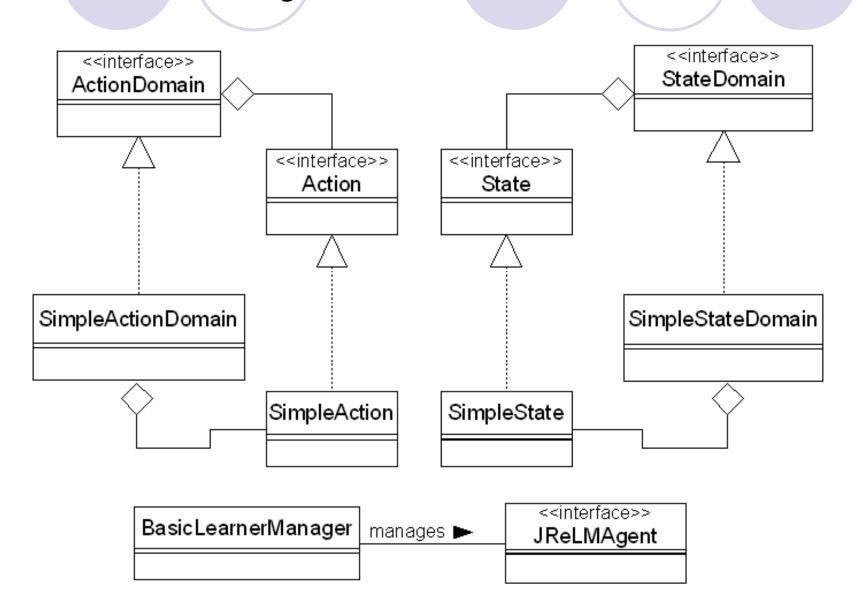
- Motivated by Sutton's and Barto's description of Reinforcement Learning\*
- Component-based
  - Plug into client defined agents
- Flexible
  - Arbitrary simulation contexts
  - Arbitrary agents
- Extensible
  - Object-oriented design
  - Documentation (Javadocs)

<sup>\*</sup> Reinforcement Learning: An Introduction http://www.cs.ualberta.ca/~sutton/book/the-book.html

### **Package Hierarchy**



### edu.iastate.jrelm.core



# Action, ActionDomain, State, StateDomain

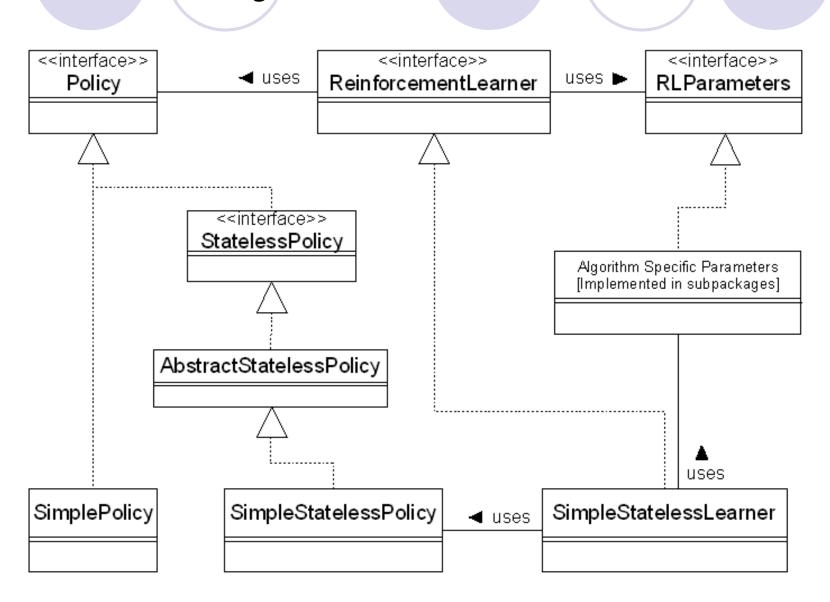
- Interfaces, not classes
- Important! Separates representation from implementation
- Flexibility: Applied to wide variety of simulation contexts
- Limitations:
  - Burden of domain implementation on the client.
    Hard to avoid without over-customization.
  - Discrete, finite domains only

# SimpleAction, SimpleState, SimpleActionDomain, SimpleStateDomain



- Basic implementation of the domain interfaces
- Wrappers around other objects, Collections
- Bridge between existing action choice/world states and JReLM
- Help ease burden in simpler simulations

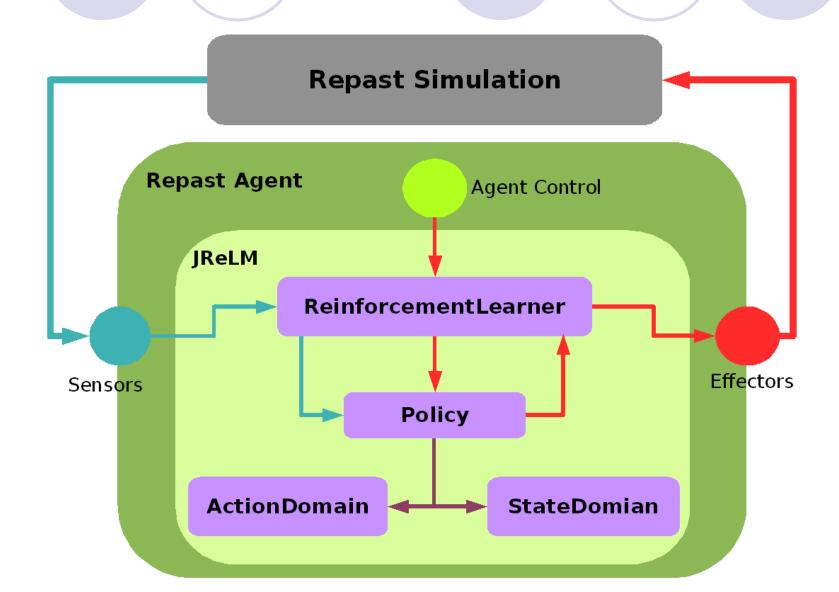
### edu.iastate.jrelm.rl



#### Base learning components

- ReinforcementLearner
  - Interface for all RL implementations (learners)
  - Work with an ActionDomain, a Policy, and a sometimes a StateDomain
- Policy
  - Mapping from State-Action pairs to probability values
    - Distributions for action choice likelihood
  - Generate new action choices
  - Compatible with any ActionDomain and StateDomain
- StatelessPolicy
- RLParameters
  - Encapsulate parameters for an algorithm
  - Used in building custom GUI

### Interaction of JReLM components



# Simple\*

- SimplePolicy and SimpleStatelessPolicy
  - Basic implementations of Policy interfaces
- SimpleLearner and SimpleStatelessLearner
  - Tie together all pre-implemented learners
  - Algorithm to use determined by the type of RLParameters given
  - May be given Collections as domains
  - Simplified use, but limited

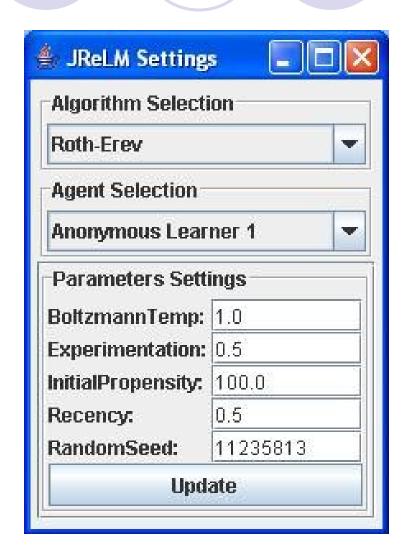
## **Graphical User Interface**

#### Goals:

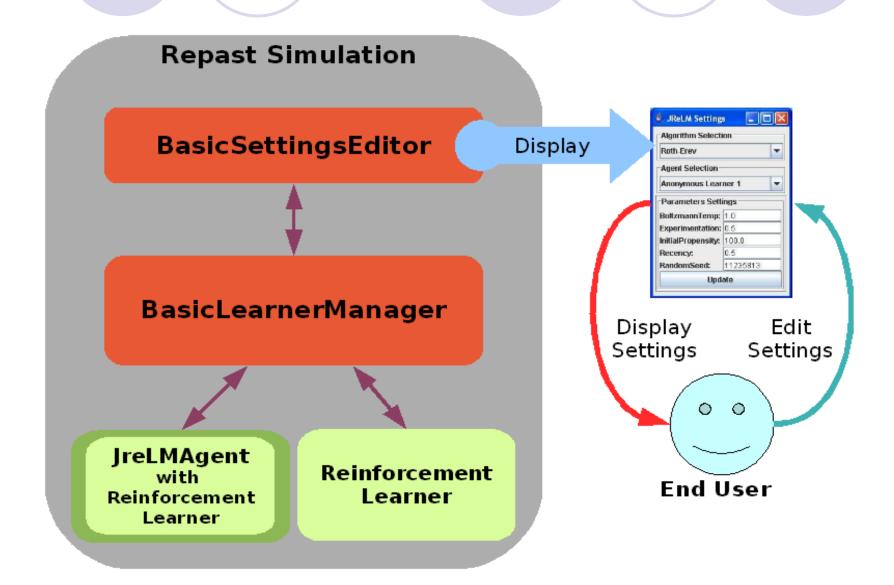
- Allow the user to modify learning settings without programming
- Track and manage all learning methods used in a model

#### Challenge:

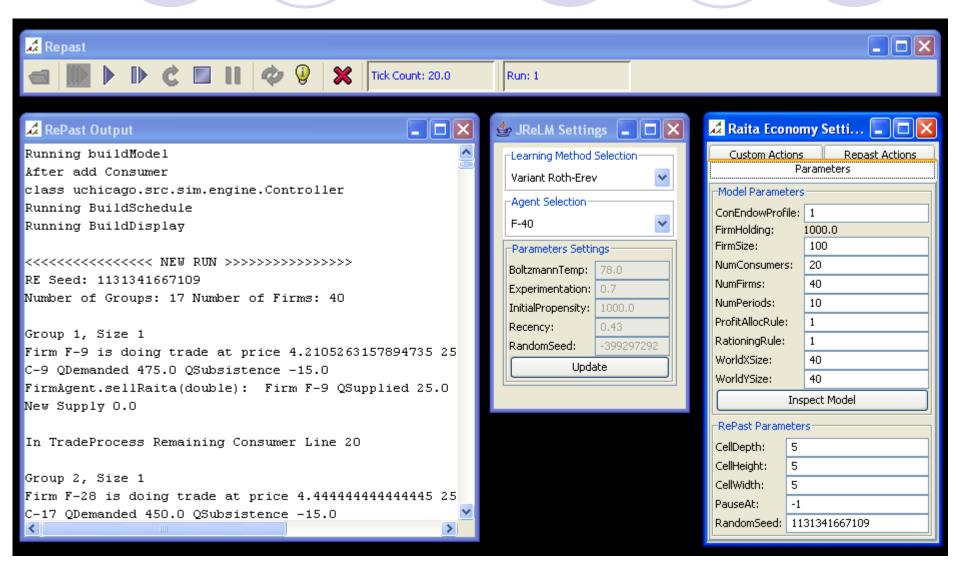
How to do this in arbitrary agents and models?



### Graphical User Interface cont.



### Graphical User Interface cont.



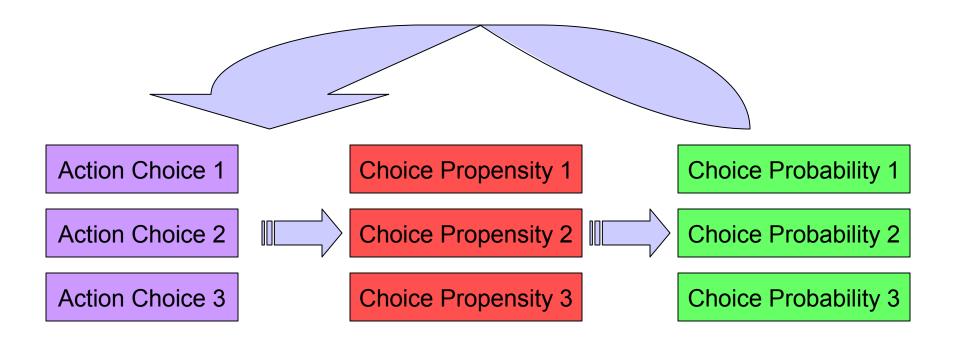
# Pre-Implemented Reinforcement Learning Algorithms

- Assist novice programmer
- Convenience for experienced programmer
- Compatible with any action and state space that can be represented by an ActionDomain or StateDomain class

#### Roth-Erev Reinforcement Learning

- Originally developed by Alvin E. Roth and Ido Erev
  - Attempt to model how humans play in repeated games against multiple strategic players
- Later modified by Nicolaisen, Petrov and Tesfatsion
  - Problem encountered with zero-valued rewards

#### **Roth-Erev Algorithm Structure**



 Maintains action choice propensities which are translated into action choice probabilities

### **Algorithm Outline**

- 1. Initialize action propensities to an initial propensity value. Initialize the action choice probabilities to a uniform distribution.
- 2. Generate choice probabilities for all actions using current propensities.
- 3. Choose an action according to the current choice probability distribution.
- 4. Update propensities for all actions using the reward for the last chosen action.
- 5. Repeat from step 2.

#### The update and experience functions

#### **Parameters**

- q<sub>0</sub> Initial Propensity
- $\epsilon$  Experimentation
- $\phi$  Recency:

#### **Variables**

- j Current action choice
- q<sub>i</sub> Propensity for j
- k Last action chosen
- r<sub>k</sub> Reward for k
- t Current timestep
- N Number of actions

$$q_{j}(t+1) = [1-\phi]q_{j}(t) + E_{j}(\epsilon, j, k, t)$$

$$E_{j}(\epsilon, j, k, t) = \begin{cases} r_{k}(t)[1 - \epsilon] & \text{if } j = k \\ r_{k}(t)\frac{\epsilon}{N-1} & \text{if } j \neq k \end{cases}$$

## Probability function

Proportional distribution

$$p_j(t) = \frac{q_i(t)}{\sum_{m=1}^{n} q_m(t)}$$

# Variation of Roth-Erev

 Nicolaisen, Petrov and Tesfatsion\* modified the experience function in response to a problem with learning in the face of zero-value rewards.

$$E_{j}(\epsilon, k, t) = \begin{cases} r_{k}(t)[1 - \epsilon] & \text{if } j = k \\ q_{j}(t) \frac{\epsilon}{N-1} & \text{if } j \neq k \end{cases}$$

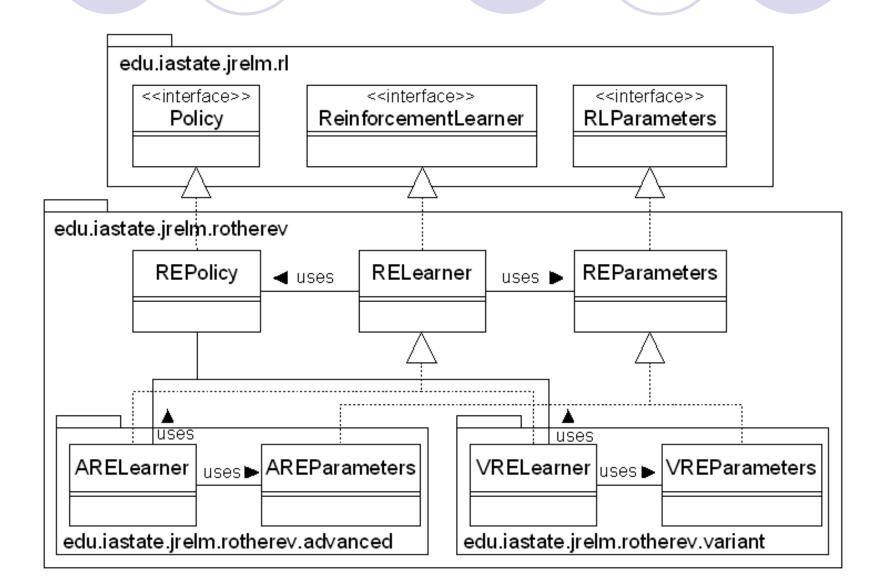
<sup>\*</sup> Nicolaisen, J., Petrov, V., and Tesfatsion, L. *Market Power and Efficiency in a Computational Electricity Market with Discriminatory Double-auction Pricing*. IEEE Transactions on Evolutionary Computing 5, 5 (October 2001), 504–523.

#### Gibbs-Boltzmann distribution

- Handle negative propensities
- T temperature parameter
  - Static, no temperature schedule

$$p_j(t) = \frac{e^{q_j(t)/T}}{\sum_{i=1}^n e^{q_i(t)/T}}$$

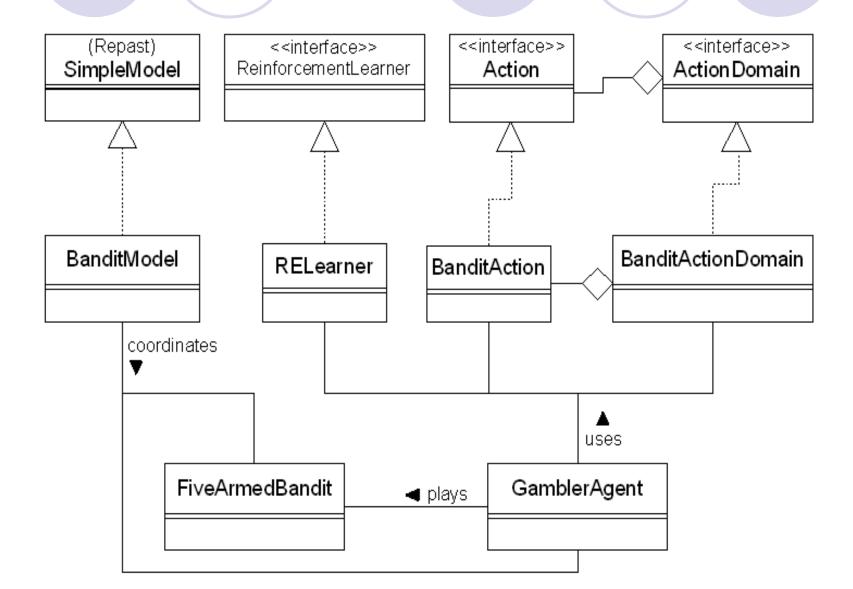
### edu.iastate.jrelm.rotherev



#### Implementation of the Roth-Erev family

- RELearner (Roth-Erev Learner)
  - Base implementation of the original algorithm
  - REParameters
  - REPolicy
- VRELearner (Variant Roth-Erev Learner)
- ARE (Advanced Roth-Erev Learner)
  - Core structure with advanced, customizable features

### edu.iastate.jrelm.demo.bandit



# The Raita Economy: An illustrative application

 Repast simulation developed by Somani and Tesfatsion



 Examine market concentration in relation to market power in a dynamic, single product (raita) economy

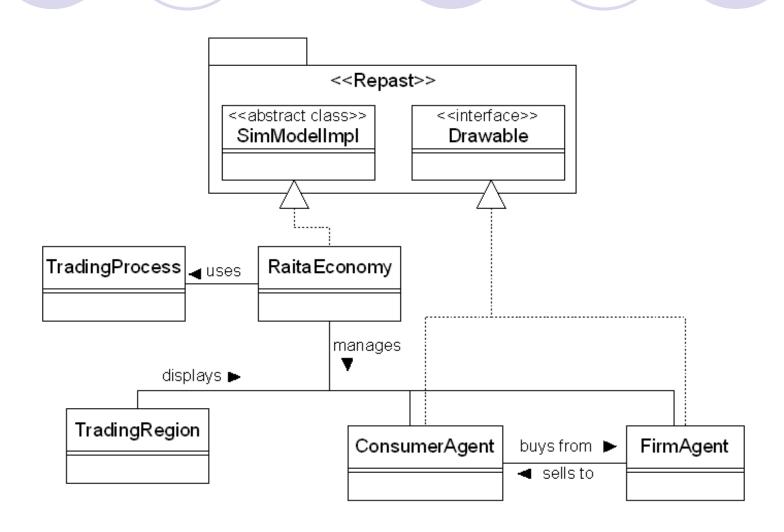
# Market Concentration and Market Power

- Market concentration: the degree to which the majority of market activity is performed by a minority of the participants.
- Market power: the degree to which a participant may profitably influence prices away from competitive levels.

# Market Concentration and Market Power cont.

- Measures of market concentration are often used as indicators of market power.
- This model examines how well three common measures predict the rise of market power in a simple dynamic production economy

## RaitaEconomy class structure



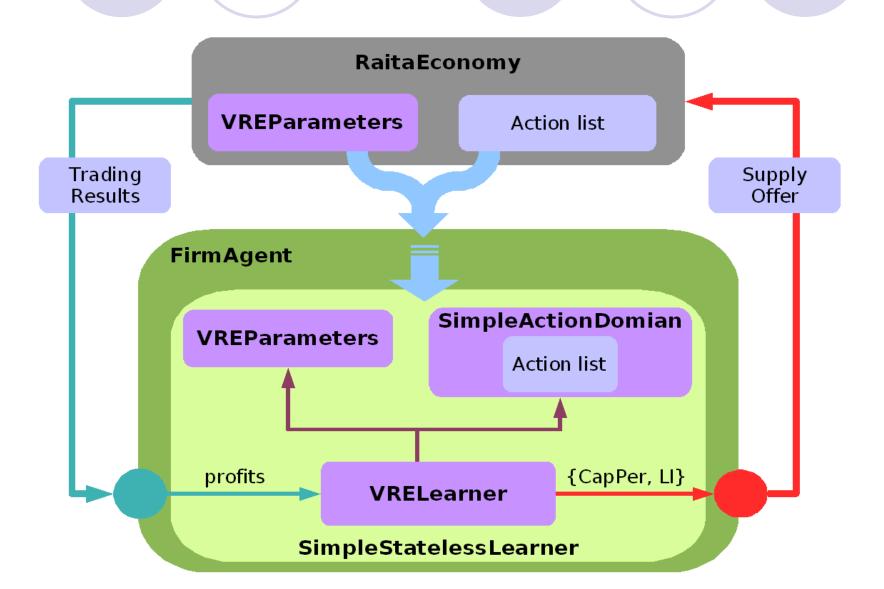
#### ConsumerAgent

- Simple, reactive agent
- Gains utility by consuming raita
- Seeks raita at the lowest available price
- Dies if subsistence needs are not met

## **FirmAgent**

- Strategic, learning agent
- Gain profit by producing and selling raita
- May adjust production and price level every trading period
  - supply offers: Production quantity and unit price
- Can also invest profits in expanding production capacity
- Exits market if it goes bankrupt

## JReLM in the RaitaEconomy



#### JReLM in the Raita Economy cont.

- Raita Economy still under construction
- First research model to use JReLM
- Balance of complexity
  - Market content more complex than the, multi-agent
  - Still simpler than other context (e.g. The AMES project)
- Valuable experience
  - What needs arise in an actual research context
  - Our How usable is JReLM?

#### **Testing and Validation**

- Unit testing of JReLM using JUnit\*
  - Suite of tests have been built along the way
  - Still expanding
- Validation of Roth-Erev family
  - Are they behaving as expected?
  - Bandit Demo: Simple, single agent context
  - Raita Economy: More complex, multi-agent context

<sup>\*</sup> JUnit is a Java unit testing package available at http://www.junit.org/index.htm

## Ongoing and future work

- Expansion of RL methods library
- Investigation into additional methods
  - Appropriate for multi-agent contexts
  - Appropriate for Social Simulation
- Improvement of the GUI
  - Integration into the Repast control panel
  - Improve management of groups of agents

# Agent-Based Modeling of Electricity Systems (AMES)

- Federal Energy Regulatory Commission
  Wholesale Power Market Platform
- AMES: Repast model designed to test the economic reliability of the WPMP
- JReLM: adaptive pricing and quantity offers for generators
- Bulk Energy Transportation Networks\*
  - NSF funded
  - Study integrated energy networks

<sup>\*</sup> Lead by primary investigator J. McCalley and co-PIs S. Ryan, S. Sapp, and L. Tesfatsion

# The NISAC Agent-Based Laboratory for Economics

- National Infrastructure and Analysis Center (NISAC)
  - Joint effort between Los Alamos and Sandia National Labs
  - Funded by the Department of Homeland Security
  - Examine critical national infrastructure
- N-ABLE (at Sandia):
  - Agent-based simulation modeling platform
- JReLM architecture and interaction, starting point for expanded adaptive behavior in N-ABLE

#### JReLM Distribution with Repast

- Repast an Open Source project
- Discussion with Repast developers
  - Inclusion of JReLm into the RepastJ package
- Requires a demonstration
- Goal
  - complete testing and validation of JReLM in time for Repast's next release



